# Effects of humidity and temperature on quality factor of micro-beam resonators in atmospheric pressure and gas rarefaction

Nguyen Chi Cuong<sup>1\*</sup>, Trinh Xuan Thang<sup>1</sup>, Lam Minh Thinh<sup>1</sup>, Vuong Dinh Duy Phuc<sup>1</sup>, Phan Minh Truong<sup>2</sup>, Truong Huu Ly<sup>1</sup>, Ngo Vo Ke Thanh<sup>1</sup>, Le Quoc Cuong<sup>1</sup>

<sup>1</sup>Research Laboratories of Saigon High-Tech Park, Lot 13, N2 Street, Saigon High-Tech Park, Tan Phu Ward, District 9, Ho Chi Minh City, Vietnam <sup>2</sup>Institute for Computational Science and Technology, SBI Building, Quang Trung Software City, Tan Chanh Hiep Ward, District 12, Ho Chi Minh City, Vietnam

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### Abstract:

At atmospheric pressure (p=101325 Pa), the effects of humidity and temperature on moist air become important when discussing the quality factor of micro-cantilever and micro-bridge resonators. The squeeze film damping (SFD) problem, the dominant damping source for micro-beam resonators, is modelled using the modified molecular gas lubrication (MMGL) equation with finite element modelling (FEM) in the eigenvalue problem. The MMGL equation is modified with the effective viscosity of moist air ( $\mu_{eff}$ ) to account for the effects of humidity and temperature. Other damping sources, such as thermoelastic damping (TED) and the support loss of micro-beam resonators, are also calculated. The quality factor of micro-beam resonators is then discussed over a wide range of temperatures and relative humidity levels at atmospheric pressure and gas rarefaction. The results show that the quality factor of micro-cantilever and micro-bridge resonators increases as both humidity and temperature rise in atmospheric pressure and gas rarefaction. Furthermore, the quality factor of a micro-bridge resonator with changes in humidity and temperature is significantly higher than that of a micro-cantilever resonator in atmospheric pressure and gas rarefaction.

Keywords: micro-beam resonators, quality factor, relative humidity, squeeze film damping, temperature.

Classification numbers: 2.1, 2.3

### 1. Introduction

Micro-beam resonators [1] are utilised in many Micro-Electro-Mechanical Systems (MEMS) sensor applications for environmental monitoring [e.g., temperature (T), humidity (RH), pollutant gases] [2, 3]. The advantages of temperature and humidity MEMS sensors based on MEMS technology include a wide detection range, rapid resonant response, and high precision. However, in moist air, the detection of temperature and water vapour plays a pivotal role in many MEMS sensor applications for environmental monitoring [4].

In MEMS resonators, the quality factor is the primary outcome when micro-beam resonators operate at atmospheric pressure. External SFD is one of the significant damping sources of MEMS resonators as airflow is squeezed in the gap spacing between a microbeam and its surrounding substrate [5]. In addition, TED [6-9] and support loss [10] are other damping sources for micro-beam resonators. For micro-beam structures of resonators, three kinds of damping sources - SFD, TED, and support loss - which are more dominant than other damping sources, have been considered to accurately evaluate the quality factor of micro-beam resonators [11]. At atmospheric pressure, the quality factor of microbeam resonators is highly influenced by the effects of temperature (T) and humidity (RH) due to the increased viscous damping of moist air. Thus, the effects of temperature and relative humidity are crucial to discuss when aiming to improve the quality factor of micro-beam resonators since the transverse vibration of micro-beam resonators is significantly resisted by the SFD.



<sup>\*</sup>Corresponding author: Email: cuong.nguyenchi@shtplabs.org

In gas rarefaction, atmospheric pressure (p=101325Pa) is introduced into a narrow air gap spacing  $(h_0)$ . Then, slip flow occurs on the micro-beam and substrate surfaces. Hence, the effect of gas rarefaction becomes significant on the dynamic performance of MEMS resonators, even at atmospheric pressure and ultra-thin gap spacing [11, 12]. To account for the effects of temperature and relative humidity in atmospheric pressure and gas rarefaction, the effective viscosity of moist air  $(\mu_{eff} = \mu/Q_p)$ , which is defined as the ratio of the Poiseuille flow rate  $(Q_n)$ [13] and the dynamic viscosity  $(\mu)$  [14] of moist air, modifying the MMGL equation for the SFD problem. As a result, the influences of temperature and relative humidity on the quality factor of micro-beam resonators can be addressed in both atmospheric pressure and gas rarefaction. Existing literature has examined the effects of temperature and relative humidity on the quality factors of MEMS resonators under atmospheric pressure [15-19]. Consequently, the quality factor of micro-cantilevers is heavily influenced by temperature and relative humidity in the atmospheric environment. However, the effects of temperature and relative humidity of moist air on the quality factor of micro-bridge resonators in atmospheric pressure and gas rarefaction have not yet been considered.

In this article, the impacts of temperature and relative humidity of moist air on the quality factor of microbridge resonators in atmospheric pressure and gas rarefaction for environmental monitoring are studied. The MMGL equation is solved using the effective viscosity  $(\mu_{aff})$  for the SFD issue to consider the effects of temperature and relative humidity across a range of pressures, from atmospheric to gas rarefaction. Previous studies have only addressed the temperature and relative humidity concerning the resonant frequency and quality factor of micro-cantilevers [18, 19] in atmospheric pressure. However, the micro-bridge structure has not been explored and discussed to date. In this research, the quality factor of the micro-bridge resonator will be discussed and compared to enhance the quality factors of MEMS resonators in atmospheric pressure and gas rarefaction. The objective of this study is to examine the effects of temperature and relative humidity of moist air in order to optimise the quality factors of MEMS resonators based on the micro-bridge structure for environmental monitoring in both atmospheric pressure and gas rarefaction.

### 2. Materials and methods

2.1. The modified molecular gas lubrication equation for air damping of micro-beam resonators



Fig. 1. Transverse vibration of micro-beam or micro-bridge resonators under air film damping.

In Fig. 1, the micro-bridge structure is used to discuss the effects of temperature and relative humidity on the quality factor of MEMS resonators in atmospheric pressure and gas rarefaction. In a moist air environment, the transverse motion of micro-beam resonators is resisted by the air film damping with a certain gas film pressure  $(\bar{p}(x, y, t))$ . The Poiseuille flow rate  $(Q_p)$  occurs in an ultra-thin gap spacing  $(h_q)$ . In this instance, an isothermal air squeeze film is assumed for all the edges of the rectangular micro-bridge. The micro-beam temperature is assumed to be the same as the ambient temperature  $(T=T_q)$ . A new MMGL equation [11] is utilised to model the SFD problem in order to obtain the pressure variations of the gas film as:

$$\frac{\partial}{\partial x} \left( \frac{\rho h^3}{12\mu_{eff}(RH,T)} \frac{\partial p}{\partial x} \right) + \frac{\partial}{\partial y} \left( \frac{\rho h^3}{12\mu_{eff}(RH,T)} \frac{\partial p}{\partial y} \right) = \frac{\partial}{\partial t} \left( \rho h \right) \quad (1)$$

where *RH* is the water vapor relative humidity (%); *p* is the air pressure,  $\rho$  is the density of moist air; *h* is the air gap spacing; *T* is the ambient temperature (°C).

The water vapor molar fraction of moist air [14] is expressed as:

$$x_{\nu} = \frac{n_{\nu}}{n_{\nu} + n_a} = \frac{p_{\nu}}{p} \tag{2}$$

where  $p_v$  is the water vapor partial pressure; p is the total pressure partial pressure;  $x_v$  is the water vapor mole fraction;  $n_v$  and  $n_a$  are the water vapor and dry air mole numbers, respectively.

The relative humidity (*RH*) of moist air [14] is given by:

$$RH = \frac{x_v}{x_{sv}} = \frac{p_v}{p_{sv}} \tag{3}$$

with

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$$x_{\nu} = x_{s\nu} \times RH \tag{4}$$

where  $p_v$  is the water vapor partial pressure;  $p_{sv}$  is the water vapor saturated pressure at a given temperature;  $x_{sv}$  is the saturated water vapor molar fraction.

The water vapor molar fraction  $(x_{y})$  can be calculated as:

$$x_{\nu} = f(p,T) \times \frac{p_{\nu}}{p} = f(p,T) \times RH \times \frac{p_{s\nu}}{p}$$
(5)

with the total pressure (p) of moist air is given by:

$$p = p_{\nu} + p_a \tag{6}$$

where  $p_a$  is the partial pressure of dry air.

The enhancement factors (f(p, T)) [20] are calculated by:

$$f(p,T) = \exp\left[\alpha \times \left(1 - \frac{p_{sv}}{p}\right) + \beta \times \left(\frac{p}{p_{sv}} - 1\right)\right]$$
(7)

with

$$\alpha = \sum_{i=1}^{4} A_i \times T^{(i-1)} \tag{8}$$

and

$$\beta = \exp\left(\sum_{i=1}^{4} B_i \times T^{(i-1)}\right) \tag{9}$$

where the numerical values of the coefficients in Eqs. (8) and (9) are:  $A_1=3.53624\times10^4$ ,  $A_2=2.93228\times10^{-5}$ ,  $A_3=2.61474\times10^{-7}$ ,  $A_4=8.57538\times10^{-9}$ ,  $B_1=-10.7588$ ,  $B_2=6.32529\times10^{-2}$ ,  $B_3=-2.53591\times10^{-4}$ , and  $B_4=6.33784\times10^{-7}$ , in the temperature range between 0 and 100°C.

The saturated vapor pressure  $(p_{yy})$  [21] is expressed by

$$p_{sv} = 10^3 \times 0.1 \times 10^e \tag{10}$$

where

$$e = E_0 + E_1 \left( 1 - \frac{273}{T + 273} \right) - E_2 \log_{10} \left( \frac{T + 273}{273} \right) + E_3 \left( 1 - 10^{-8.2969 \times \left( \frac{T + 273}{273} - 1 \right)} \right) + E_4 \left( 10^{4.76955 \times \left( 1 - \frac{273}{T + 273} \right)} \right)$$

and

 $E_0 = 0.78614$ ,  $E_1 = 10.79574$ ,  $E_2 = 5.028$ ,  $E_3 = 1.50475 \times 10^{-4}$ ,  $E_4 = 0.42873 \times 10^{-3}$ .

At atmospheric pressure, the dynamic viscosity of humid air  $(\mu)$  [14] is calculated by:

$$\mu = \frac{\mu_a \times (1 - x_v)}{[(1 - x_v) + x_v \phi_{av}]} + \frac{x_v \times \mu_v}{[x_v + (1 - x_v) \times \phi_{va}]}$$
(11)

where  $\mu_a$  and  $\mu_v$  are the dynamic viscosity of dry air and water vapor, respectively, as:

$$\mu_a = M_{A_0} + \sum_{i=1}^4 M_{A_i} (T + 273)^i \tag{12}$$

$$\mu_{\nu} = M_{\nu_0} + M_{\nu_1} T \tag{13}$$

and

 $M_{A0}$ =-9.8601×10<sup>-7</sup>,  $M_{A1}$ =9.08012×10<sup>-8</sup>,  $M_{A2}$ =-1.1764×10<sup>-10</sup>,  $M_{A3}$ =1.2350×10<sup>-13</sup>,  $M_{A4}$ =-5.797×10<sup>-17</sup>,  $M_{V0}$ =8.058×10<sup>-6</sup>, and  $M_{V1}$ =4.0005×10<sup>-8</sup>

Also,  $\Phi_{av}$  and  $\Phi_{va}$  are calculated by

$$\Phi_{av} = \frac{\sqrt{2}}{4} \left( 1 + \frac{M_a}{M_v} \right)^{-0.5} \times \left[ 1 + \left( \frac{\mu_a}{\mu_v} \right)^{0.5} \times \left( \frac{M_v}{M_a} \right)^{0.25} \right]^2$$
(14)

$$\Phi_{\nu a} = \frac{\sqrt{2}}{4} \left( 1 + \frac{M_{\nu}}{M_{a}} \right)^{-0.5} \times \left[ 1 + \left( \frac{\mu_{\nu}}{\mu_{a}} \right)^{0.5} \times \left( \frac{M_{a}}{M_{\nu}} \right)^{0.25} \right]^{-1} (15)$$

where  $\Phi_{av}$  and  $\Phi_{va}$  are interaction factors for calculating  $\mu_a$  and  $\mu_v$ , respectively;  $M_{Ai}$  and  $M_{Vi}$  are interpolation constants for the dynamic viscosity of dry air and water vapor, respectively;  $M_a$  and  $M_v$  are the dry air and water vapor molar mass, respectively.

For the effect of gas rarefaction, the Poiseuille flow rate  $Q_p(D)$  [13] is derived for arbitrary inverse Knudsen number (*D*) with the accommodation coefficients of two surfaces ( $\alpha_1 = \alpha_2 = 1.0$ ) by:

$$Q_P(D) = 1 + 3\sqrt{\pi} \times a \times D^{-1} + 6b \times D^c \tag{16}$$

where *a*=0.01807, *b*=1.35355, *c*=-1.17468.

The inverse Knudsen number (*D*) is expressed by:

$$D = \frac{\sqrt{\pi}}{2K_n} = \frac{\sqrt{\pi}h}{2\lambda} \tag{17}$$

where *h* is the gap spacing.

The mean free path of gas is estimated from the kinetic theory of gases [22] is expressed as:

$$\lambda = \frac{RT}{\sqrt{2}\pi \times N_a d^2 p} \tag{18}$$

where *d* is the gas molecular diameter; R=8.314 (J/mol) is the gas constant;  $N_{a}=6.0221\times10^{23}$  is Avogadro's number.

From Eqs. (3), (7), and (18), the mean free path of moist air ( $\lambda$ ) can be expressed by:

$$\lambda = \frac{\lambda_0 p'_0 T}{p T'_0} = \frac{\lambda_0 p'_0 T}{(p_a + RH \cdot p_{SW}) T'_0},$$
(19)

where  $\lambda_0$ =66.5 nm,  $p'_0$ =101325 Pa,  $T'_0$ =300 K are the reference gas mean free path, reference pressure, and reference temperature, respectively.

The effective viscosity  $(\mu_{eff})$  of moist air [11] is expressed by:

$$\mu_{eff} = \frac{\mu}{Q_P} \tag{20}$$

where  $\mu_{eff}$  (*RH*, *T*) can be used to consider the effects of temperature and relative humidity in atmospheric pressure and gas rarefaction.

### 2.2. The linear transverse vibration equation for micro-beam resonators

Under small displacement (*w*), the linear transverse vibration equation of a micro-beam in Fig. 1 governs the transverse displacement [23], which is expressed as:

$$D_p\left(\frac{\partial^4 w}{\partial x^4} + 2\frac{\partial^4 w}{\partial x^2 \partial y^2} + \frac{\partial^4 w}{\partial y^4}\right) + \rho_m t_b \frac{\partial^2 w}{\partial t^2} = -\bar{p}(x, y, t) \quad (21)$$

where  $D_P (=Et_b^3/12(1-v^2))$  is the rigidity of the material; *E* is Young's modulus; v is the Poisson's ratio;  $t_b$  is the structural thickness;  $\bar{p}(x, y, t)$  is the gas pressure variation; w(x, y, t) is the transverse displacement at positions along the structure (x, y) over time (t);  $p_m$  is the density of the material.

For a micro-cantilever beam [18, 19], single-clamped boundary conditions are used at one edge of the cantilever (x=0):

w(0, y, t) = 0 (22)

$$\frac{\partial w(0,y,t)}{\partial x} = 0 \tag{23}$$

and three free boundaries are used at the other edges of the cantilever  $(x=l_b, y=0, \text{ and } y=w_b)$ :

$$\frac{\partial^2 w(\ell_b, y, t)}{\partial x^2} = \frac{\partial^3 w(\ell_b, y, t)}{\partial x^3} = 0$$
(24)

$$\frac{\partial^2 w(x,0,t)}{\partial y^2} = \frac{\partial^3 w(x,0,t)}{\partial y^3} = 0$$
(25)

$$\frac{\partial^2 w(x, w_b, t)}{\partial y^2} = \frac{\partial^3 w(x, w_b, t)}{\partial y^3} = 0$$
(26)

For a micro-bridge, the two double-clamped boundary conditions are set at two edges of the micro-bridge (x=0) and ( $x=l_{k}$ ):

$$(0, y, t) = w(\ell_b, y, t) = 0$$
(27)

$$\frac{\partial w(0,y,t)}{\partial x} = \frac{\partial w(\ell_b,y,t)}{\partial x} = 0$$
(28)

and two free-edge conditions at other edges of the microbridge  $(y=0, y=w_b)$ :

$$\frac{\partial^2 w(x,0,t)}{\partial y^2} = \frac{\partial^3 w(x,0,t)}{\partial y^3} = 0$$
(29)

$$\frac{\partial^2 w(x, w_b, t)}{\partial y^2} = \frac{\partial^3 w(x, w_b, t)}{\partial y^3} = 0$$
(30)

### 2.3. Quality factors of micro-beam resonators

In the eigen-value problem, the quality factor of the MEMS resonators in the SFD problem is numerically estimated by obtaining the eigenvalue ( $\overline{\lambda} = \delta + i\omega$ ). Then,

the quality factor for the SFD problem  $(Q_{SFD})$  [14] can be calculated as the ratio between the natural frequency  $(\omega_0) (Im|\bar{\lambda}|)$  and the damping factor  $(\delta) (\delta) (Re|\bar{\lambda}|)$  by:

$$Q_{SFD} = \left| \frac{Im(\bar{\lambda})}{2 Re(\bar{\lambda})} \right| = \frac{\omega_0}{2\delta}$$
(31)

where  $\bar{\lambda} (= \delta + i\omega)$  is the complex eigenvalue.

In micro-beam resonators, the total quality factor  $(Q_T)$  can be evaluated by the quality factor of the main damping sources of the SFD  $(Q_{SFD})$ , TED  $(Q_{TED})$ , and the support loss  $(Q_{sup})$ . Therefore, the total quality factor  $(Q_T)$  of the micro-cantilever and bridge beam resonators are calculated as:

$$\frac{1}{Q_T} = \frac{1}{Q_{SFD}} + \frac{1}{Q_{TED}} + \frac{1}{Q_{sup}}$$
(32)

where the basic operating conditions are listed in Table 1.  $Q_{TED}$  is calculated by C. Zener's models [6, 7] (Eq. (14) in [7]) in Table 2.  $Q_{sup}$  is also calculated by Z. Hao, et al. (2003) [10] (Eq. (18) in Table 3).

Table 1. Basic geometric and operating conditions ofMEMS resonators.

Symbol	Description	Values
l <sub>b</sub>	Length of beam	250 µm
w <sub>b</sub>	Width of beam	10 µm
t <sub>b</sub>	Thickness of beam	1 μm
Ε	Young's modulus of silicon	130×10 <sup>9</sup> Pa
$\rho_m$	Density of silicon	2330 kg/m <sup>3</sup>
v	Poisson's ratio of silicon	0.28
$\alpha_{_m}$	Thermal expansion coefficient of silicon	2.6×10 <sup>-6</sup> 1/K
κ	Thermal conductivity of silicon	90 W/(m.K)
$C_p$	Specific heat capacity of silicon cantilever	700 J/(kg.K)
$h_0$	Basic gas film thickness	4 μm
$T_0$	Basic temperature	50°C
р	Ambient pressure of moist air	101325 Pa
Т	Ambient temperature	0-100°C
RH	Relative humidity of moist air	0-100%

Resonators	Mode shape	(Hz)	<b>Q</b> <sub>TED</sub> in FEM [24]	<b>Q</b> <sub>Zener</sub> in Zener [6, 7]	% Error $\left \frac{Q_{TED}-Q_{Zener}}{Q_{TED}}\right  \times 100\%$
Cantilever		19,344	21,738,340	22,589,923	3.77
Bridge		123,539	3,283,491	3,491,068	5.94

Table 2. The quality factor of thermoelastic damping (TED) ( $Q_{TED}$ ) for micro-beam resonators in the 1<sup>st</sup> mode of vibration.

Table 3. The quality factor of support loss ( $Q_{sup}$ ) for micro-beam resonators in the 1<sup>st</sup> mode of vibration.

Resonators	Mode shape	$f_n$ (Hz)	$C_{(F(n))}$	$\lambda_{T}$	$\lambda_T / w_b$	<b>Q</b> <sub>sup</sub> [10]
Cantilever		19,344	2.081	0.241	24,133	32,515,625
Bridge		123,539	0.638	0.038	3,778	9,968,750

### 3. Results and discussion



3.1. Effective viscosity,  $\mu_{eff}(RH, T)$ 

Fig. 2. Effective viscosity of moist air  $(\mu_{eff})$  versus temperature (*T*) for different relative humidity values (*RH*) at atmospheric pressure.

In Fig. 2, the effective viscosity of moist air  $(\mu_{eff})$ , Eq. (20), in dry air linearly increases with *T* in the dry air (*RH*=0%). Meanwhile,  $\mu_{eff}$  of moist air decreases gradually as temperature and relative humidity increase. Therefore, we note that the effective viscosity  $(\mu_{eff})$  decreases more significantly as temperature and relative humidity increase.

## 3.2. Effects of temperature (T) and relative humidity (RH) on quality factors ( $Q_{SFD}, Q_{T}$ )

In Table 2, the results show that  $Q_{TED}$  and  $Q_{Zener}$  are very high because the TED is very small in the 1<sup>st</sup> mode of cantilever and bridge resonators. Moreover,  $Q_{TED}$  from the FEM (COMSOL Multiphysics) [24] and  $Q_{Zener}$  from the C. Zener's models [6, 7] are nearly identical with an error of less than 5.94%. Therefore,  $Q_{TED}$  in the FEM [24] can be accurately used to calculate the total quality factor  $(Q_T)$  of MEMS resonators.

In Table 3, the result showed that  $Q_{sup}$  is very high because the support loss is very small in the 1<sup>st</sup> mode of the resonators. Also, the results of  $Q_{sup}$  can be used to calculate the total quality factor ( $Q_T$ ) of micro-beam resonators.

In Fig. 3, the obtained results of  $Q_{SFD}$  and  $Q_T$  of the micro-beam resonators are nearly identical over a wide range of temperature and humidity values at atmospheric pressure (p=101325 Pa). Therefore,  $Q_T$  can be calculated by the main contribution of  $Q_{SFD}$  because the SFD is the dominant damping source and the other damping sources ( $Q_{TED}, Q_{sup}$ ) are negligible in the 1<sup>st</sup> mode of the resonator.  $Q_{SFD}$  and  $Q_T$  of dry air decreases as *T* increases.  $Q_{SFD}$  and  $Q_T$  of moist air increases as relative humidity (*RH*) increases from 0 to 100 % at atmospheric pressure. Then,  $Q_{SFD}$  and



Fig. 3. The quality factor by SFD ( $Q_{SFD}$ ) and total quality factor ( $Q_{\tau}$ ) versus ambient temperature (T) for different relative humidity (*RH*) values in the 1<sup>st</sup> modes of MEMS cantilever and bridge beam resonators at atmospheric pressure (*p*=101325 Pa).

 $Q_T$  of moist air increases with temperature and relative humidity at p=101325 Pa. Also,  $Q_{SFD}$  and  $Q_T$  of the micro-cantilever with temperature and relative humidity is lower than that of the micro-bridge because of SFD influences on the cantilever being much stronger than that on the micro-bridge.

### 4. Conclusions

In these results, the quality factors of micro-beam resonators are numerically calculated by solving the MMGL equation, the equation of transverse vibration of the micro-beam, and their appropriate boundary conditions simultaneously using the FEM. The effective viscosity ( $\mu_{eff}(RH, T)$ ) is utilised to modify the MMGL equation to consider the effects of temperature and relative humidity in atmospheric pressure and gas rarefaction. Some of the obtained results are shown as follows: (a) The quality factor of micro-beam resonators increases as the temperature and relative humidity increase in atmospheric pressure and gas rarefaction; (b) The quality factor of the micro-bridge resonator with temperature and relative humidity is much higher than that of the micro-cantilever resonator.

These highlighted results can be utilised to design for a high-quality factor and a fast resonant response of MEMS resonators. In future work, the design and fabrication process of temperature and humidity sensors based on micro-bridge resonators can be addressed and fabricated using MEMS technologies for environmental monitoring.

### **CRediT** author statement

Nguyen Chi Cuong: Supervision, Conceptualisation, Writing - Reviewing; Trinh Xuan Thang, Lam Minh Thinh, Vuong Dinh Duy Phuc, Phan Minh Truong, Truong Huu Ly, Ngo Vo Ke Thanh, Le Quoc Cuong: Reviewing and Editing.

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### **COMPETING INTERESTS**

The authors declare that there is no conflict of interest regarding the publication of this article.

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