

Improved error of electromagnetic shielding problems by a two-process coupling subproblem technique

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ABSTRACT

Introduction: The direct application of the classical finite element method for dealing with magneto dynamic problems consisting of thin regions is extremely difficult or even not possible. Many authors have been recently developed a thin shell model to overcome this drawback. However, this development generally neglects inaccuracies around edges and corners of the thin shell, which leads to inaccuracies of the magnetic fields, eddy currents, and joule power losses, especially increasing with the thickness. **Methods:** In this article, we propose a two-process coupling subproblem technique for improving the errors that overcome thin shell assumptions. This technique is based on the subproblem method to couple SPs in two-processes. The first scenario is an initial problem solved with coils/stranded inductors together with thin region models. The obtained solutions are then considered as volume sources for the second scenario, including actual volume improvements that scope with the thin shell assumptions. The final solution is, to sum up, the subproblem solutions achieved from both scenarios. The extended method is approached for the h -conformal magnetic formulation. **Results:** The obtained results of the method are checked/compared to be close to the reference solutions computed from the classical finite element method and the measured results. This can be pointed out in a very good agreement. **Conclusion:** The extended method has also been successfully applied to the practical problem (TEAM workshop problem 21, model B).

Key words: Magnetic flux density, eddy current losses, Joule power losses, thin shells, finite element method, subproblem method (SPM)

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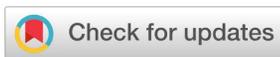
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INTRODUCTION

The direct application of the finite element method (FEM)¹ for dealing with magneto dynamic problems consisting of thin regions is extremely difficult or even not possible. Many authors² have been recently developed a thin shell (TS) model in order to overcome this drawback. However, this development generally neglects inaccuracies around edges and corners of TS, which leads to inaccuracies of the local fields (magnetic fields, eddy currents, and Joule power losses...). The aim of this study is to propose a two-process coupling subproblem (SP) technique for improving the errors appearing from the TS models that were developed in². The technique is herein based on the subproblem method (SPM) presented by many authors³⁻⁷. The technique allows to couple SPs in two-processes. The first scenario is an initial problem solved with coils/stranded inductors and thin region models; the obtained solutions are then considered as volume sources (VSs) (express as of permeability and conductivity material in conducting regions) for the second scenario including actual volume improvements that scope with the TS assumptions². The

final solution is, to sum up, the SP solutions achieved from both the scenarios. The extended method is implemented for the magnetic field density formulation and applied to a practical problem (TEAM workshop Problem 21, model B)⁸.

COUPLING SUBPROBLEM TECHNIQUE

In the strategy SP, a canonical magneto dynamic problem i , to be solved at procedure i , is solved in a domain Ω_i , with boundary $\partial\Omega_i = \Gamma_i = \Gamma_{h,i} \cup \Gamma_{b,i}$. The eddy current belongs to the conducting part $\Omega_{c,i}$ ($\Omega_{c,i} \subset \Omega_i$), whereas the stranded inductors are the non-conducting $\Omega_{nc,i}^C$, with $\Omega_{c,i} = \Omega_{c,i} \cup \Omega_{nc,i}^C$. The Maxwell's equations together with the following constitutive relations³⁻⁷.

$$\begin{aligned} \text{curl } h_i &= j_i, \quad \text{div } b_i = 0, \\ \text{curl } e_i &= -\partial_t b_i \end{aligned} \quad (1a-b-c)$$

$$\begin{aligned} b_i &= \mu_i h_i + b_{s,i}, \\ e_i &= \sigma_i^{-1} j_i + e_{s,i} \end{aligned} \quad (2a-b)$$

$$n \times e_i|_{\Gamma_e} = j_{f,i} \quad (3)$$

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where \mathbf{b}_i is the magnetic flux density, \mathbf{h}_i is the magnetic field, \mathbf{e}_i is the electric field, \mathbf{j}_i is the electric current density, μ_i is the magnetic permeability, σ_i is the electric conductivity and \mathbf{n} is the unit normal exterior to Ω_i . The surface field $j_{f,i}$ in (2 c) is a surface source (SS) expressed as changes of interface conditions (ICs) and is generally defined as a zero for classical homogeneous boundary conditions (BCs). If nonzero, it can consider as SS that account for particular phenomena presenting at the idealized thin regions between the positive and negative sides of Γ_i (Γ_i^+ and Γ_i^-). The source fields $\mathbf{b}_{s,i}$ and $\mathbf{e}_{s,i}$ in (2 a-b) are VSs. In the SPM, the changes of materials from the TS region ($i = 1, \mu_1$ and σ_1) to the volume improvement ($i = 2, \mu_2$ and σ_2) can be defined via VSs^{4-7,9}.

$$\begin{aligned} b_{s,2} &= (\mu_2 - \mu_1)h_1, \\ e_{s,2} &= (\sigma_2^{-1} - \sigma_1^{-1})j_1 \end{aligned} \quad (4 \text{ a-b})$$

The total fields can be defined via a superposition method¹, i.e.

$$b = b_1 + b_2 = \mu_2(h_1 + h_2) \quad (5 \text{ a-b})$$

$$e = e_1 + e_2 = \sigma_2^{-1}(j_1 + j_2) \quad (6 \text{ a-b})$$

FINITE ELEMENT WEAK FORMULATION

Magnetic field intensity formulation

By starting from the Ampere's law (1c), the weak conform magnetic field formulation of SP i ($i \equiv 1, 2$) can be written as³⁻⁷:

$$\begin{aligned} &\partial_t(\mu_i h_i, h'_i)_{\Omega_i} + (\sigma_i^{-1} \text{curl } h_i, \text{curl } h'_i)_{\Omega_{c,i}} \\ &- \partial_t(b_{s,i}, h'_i)_{\Omega_i} + (e_{s,i}, \text{curl } h'_i)_{\Omega_i} \\ &+ \langle [n \times e_i]_{\gamma_i}, h'_i \rangle_{\Gamma_i} \\ &+ \langle n \times e_i, h'_i \rangle_{\Gamma_i - \gamma_i} = 0, \forall h'_i \in H^1_{e,i}(\text{curl}, \Omega_i). \end{aligned} \quad (7)$$

The magnetic field \mathbf{h}_i in (7) is decomposed into parts, $\mathbf{h}_i = \mathbf{h}_{s,i} + \mathbf{h}_{r,i}$, where $\mathbf{h}_{s,i}$ is the source magnetic field defined via an imposed electric current density in the stranded inductors $\Omega_{s,i}$, that is

$$\begin{aligned} &(\text{curl } h_{s,i}, \text{curl } h'_{s,i})_{\Omega_{s,i}} = (j_{s,i}, \text{curl } h'_{s,i})_{\Omega_{s,i}}, \\ &\forall h'_{s,i} \in H^1_{e,i}(\text{curl}, \Omega_{s,i}) \end{aligned} \quad (8)$$

and $\mathbf{h}_{r,i}$ is the associated reaction magnetic field, which we have to define, i.e.

$$\begin{cases} \text{curl } h_{s,i} = j_{s,i} \text{ in } \Omega_{s,i} \\ \text{curl } h_{r,i} = 0 \text{ in } \Omega^C_{c,i} - \Omega_{s,i} \end{cases} \quad (9)$$

In the non-conducting regions $\Omega^C_{c,i}$, the reaction field $\mathbf{h}_{r,i}$ is thus defined via a scalar potential⁷.

The function space $H^1_{e,i}(\dots)$ in (7) and (8) is a curl-conform containing the basis functions for \mathbf{h}_i and $\mathbf{h}_{s,i}$ as well as for the test function h'_i and $h'_{s,i}$ (at the discrete level, this space is defined by finite edge elements); notations (\cdot, \cdot) and $\langle \cdot, \cdot \rangle$ are respectively a volume integral in and a surface integral of the product of their vector field arguments. The integral surface term

$\langle n \times e_i, h'_i \rangle_{\Gamma_i - \gamma_i}$ on Γ_h in (7) is defined as a homogeneous

Neumann BC, e.g., imposing a symmetry condition of "zero magnetic flux", i.e.

$$n \times e_i|_{\Gamma_e} = 0 \Rightarrow \mathbf{n} \bullet \mathbf{b}_i|_{\Gamma_{e,i}} = 0. \quad (10)$$

The trace discontinuity $\langle [n \times e_i]_{\gamma_i}, h'_i \rangle_{\Gamma_i}$ appearing in (7) is considered as a TS model and given as¹:

$$\begin{aligned} &\langle [n \times e_i]_{\gamma_i}, h'_i \rangle_{\Gamma_i} = \langle \mu_i \beta_i \partial_t(2h_{c,i} + h_{d,i}), h'_{c,i} \rangle_{\Gamma_i} \\ &+ \langle \frac{1}{2}[\mu_i \beta_i \partial_t(2h_{c,i} + h_{d,i}) + \frac{1}{\sigma_i \beta_i} h_{d,i}], h'_{c,i} \rangle_{\Gamma_i^+} \end{aligned} \quad (11)$$

where $h_{c,i}$ and $h_{d,i}$ are continuous and discontinuous components of \mathbf{h}_i , and β_i is a factor defined as

$$\begin{aligned} \beta_i &= \gamma_i^{-1} \tanh\left(\frac{d_i \gamma_i}{2}\right), \\ \gamma_i &= \frac{1+j}{2}, \delta_i = \sqrt{\frac{2}{\omega \sigma_i \mu_i}} \end{aligned} \quad (12)$$

for d_i and δ_i being the local thickness of the TS and skin depth, respectively.

Projected solutions between thin shell and volume improvement

The obtained solution \mathbf{h}_1 ($i=1$) in sub-domain of the TS model Ω_1 is now considered as a VS in a sub-domain of the volume improvement (current problem) Ω_2 ($i=2$). This means that at the discrete level, the source \mathbf{h}_1 solved in the mesh of the Ω_1 has to be projected in mesh Ω_2 via a projection method⁹. This can be done via its curl limited to Ω_2 , i.e.

$$\begin{aligned} &(\text{curl } h_{1-2}, \text{curl } h'_2)_{\Omega_2} = (\text{curl } \mathbf{h}_1, \text{curl } h'_2)_{\Omega_2}, \\ &\forall h'_2 \in H^1_2(\text{Curl}, \Omega_2) \end{aligned} \quad (13)$$

Where $H^1_2(\text{Curl}, \Omega_2)$ is a gauged curl-conform function space for the projected source \boxtimes_{1-2} and the test function h'_2 .

Magnetic field intensity formulation with volume improvement

The solution in (7) with the TS model (solved from the first scenario) is forced as a VS for solving the second problem (that contains an actual volume/volume improvement) through the volume integrals $\partial_t(b_{s,i}, h'_i)_{\Omega_i}$ and $(e_{s,i}, \text{curl } h'_i)_{\Omega_i}$, where $\mathbf{b}_{s,i}; \mathbf{e}$

s_i are given in (4a-b). For that, the weak formulation for a volume improvement (for example, $i=2$) is then written as

$$\begin{aligned} & \partial_t(\mu_2 h_2, h_2')_{\Omega_2} + (\sigma_2^{-1} \text{curl } h_2, \text{curl } h_2)_{\Omega_{e,i}} \\ & + \partial_t(\mu_2 - \mu_1)h_1, h_2')_{\Omega_2} \\ & + ((\sigma_2^{-1} - \sigma_1^{-1})j_1, \text{curl } h_2')_{\Omega_2} \\ & + \langle n \times e_2, h_2' \rangle_{\Gamma_2} = 0, \forall h_2' \in H_{e,2}^1(\text{curl}, \Omega_2). \end{aligned} \tag{14}$$

At the discrete level, the source fields h_1 and j_1 defined in the mesh of the TS model ($i=1$) via (7) are now projected in the mesh of the current SP/volume improvement SP ($i=2$) via (13) shown in Section Projected solutions between thin shell and volume improvement.

APPLICATION TEST

The test problem is a TEAM workshop problem 21 (model B)⁸, with two excitation coils and a magnetic steel plate (Figure 1). The thickness of the plate is 10 mm, and the electric conductivity is $\sigma = 6.484$ MS/m, the relative magnetic permeability $\mu = 200$, the frequency $f = 50$ Hz, and the exciting current of 25A. The test problem is solved in a 3-D case.

The distribution of the magnetic flux density b in a cut-plane due to the exciting/imposed current in the coils with a simplified mesh of the TS SP is shown in Figure 2.

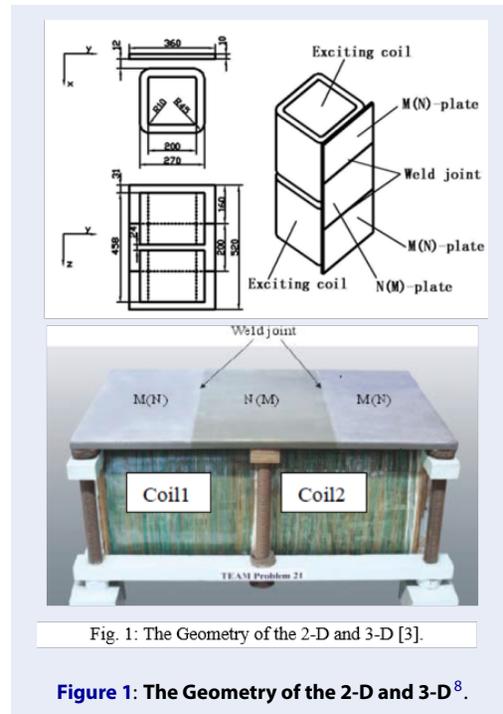


Figure 1: The Geometry of the 2-D and 3-D⁸.

The inaccuracies on the eddy current density and Joule power loss density between the TS and volume

improvement along the vertical edge (z-direction), with effects of μ , σ and f ($d = 10$ mm), are improved by important volume improvements shown in Figure 3. The significant errors near the edges and corners reach 40% with δ (skin-depth) = 2.1 mm and thickness $d = 10$ mm in Figure 3 (top), and 50% in Figure 3 (bottom) as well. The volume improvements are then checked to be close to the reference solutions (computed from FEM) for different parameters in both Figure 3. The relative improvement of the power loss density along the thin plate is presented in Figure 4. It can obtain up to 65% near the edges and corners of the TS.

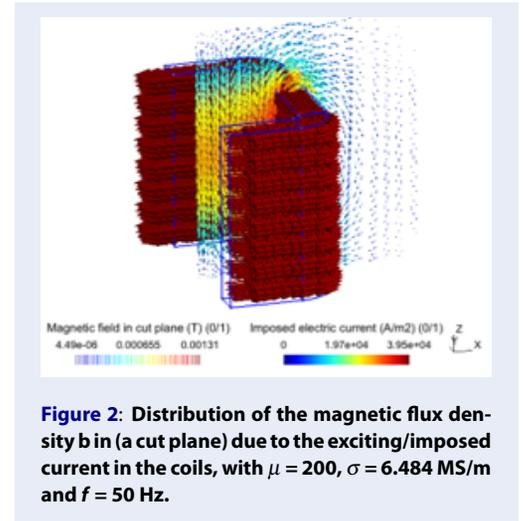


Figure 2: Distribution of the magnetic flux density b in (a cut plane) due to the exciting/imposed current in the coils, with $\mu = 200$, $\sigma = 6.484$ MS/m and $f = 50$ Hz.

The results obtained on the magnetic flux density from the volume improvement are also compared with the measured results⁸ pointed out in Figure 5. The maximum and minimum errors between two method are proximately 10.9% and 1.5%, respectively. This is said that there is a very suitable validation of the extended method.

DISCUSSION AND CONCLUSION

A two-process coupling subproblem technique with the magnetic field formulation has been successfully extended for improving errors on the local fields of magnetic flux density, eddy current density and Joule power loss density around the edges and corners of the TS approximations proposed in².

The obtained results of the method are checked to be close to the reference solution in computation of the classical FEM¹ and are also compared to be similar the measured results from a TEAM workshop problem 21 (model, B) proposed by many authors⁸. This

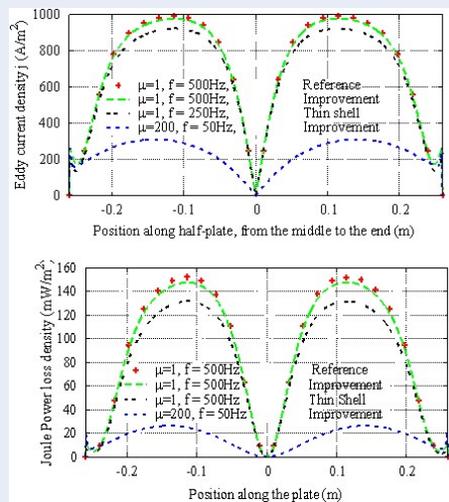


Figure 3: Eddy current density (top) and Joule power loss density (bottom) between the TS and volume solution along the vertical edge (z-direction), with effects of μ , σ and f ($d = 10$ mm).

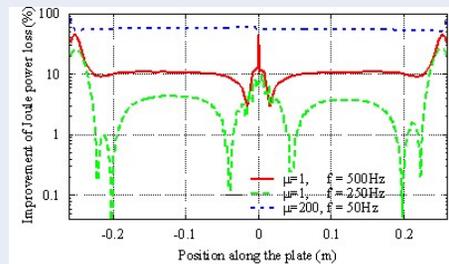


Figure 4: Relative improvement of the Joule power loss density along the plate, with the effects μ , σ and f ($d = 10$ mm).

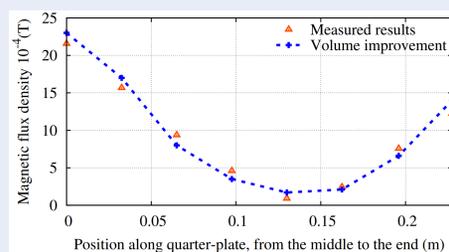


Figure 5: The comparison of the volume improvement (computed results) and measured results³ along z-direction { $x = 0.576$ m, $y = 0$ m}.

is also demonstrated that there is a very good agreement between the studied technique and experiment methods.

The developed technique has been successfully carried out with the linear case in the frequency domain.

The extension of the method could be also implemented in the time domain and the nonlinear case (proposed in¹⁰) in next study.

All the steps of the technique have been validated and applied to international test problem (TEAM workshop problem 21, model B)⁸. In particular, the achieved results is a good condition to analyze the influence of the fields to around electrical/electronic devices when taking a shielding plate into account.

COMPLETING INTERESTS

The author declares that there is no conflict of interest regarding the publication of this paper.

AUTHOR'S CONTRIBUTIONS

All the main contents, source-codes and the computed results of this article have developed by the author.

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